

1. To get the specified scale, select $100 \%$ in print settings.

(1) 20-degree incline

(3) 10-degree incline

Name:
Balboa 32U4 Balancing Robot with 80 mm wheels and bumper cage

Units: mm Material: [in]

(1) 36.8-degree incline

(3) 30-degree incline

1. To get the specified scale, select $100 \%$ in print settings.
2. Angles shown assume use of 80 mm wheels.

(2) 35 -degree incline

(4) 25-degree incline
https://www.pololu.com/product/3575

## Name:

Balboa 32U4 Balancing Robot with 80 mm wheels and bumper cage

Drawing date:
Dev code
27 June 2018
Units: mm Material:

Item number:

(1) 20-degree decline

(3) 10-degree decline

1. To get the specified scale, select $100 \%$ in print settings.
2. Angles shown assume use of 80 mm wheels.

(2) 15-degree decline

(4) 5 -degree decline


3. To get the specified scale, select $100 \%$ in print settings.
4. Angles shown assume use of 80 mm wheels.

Name:
Balboa 32U4 Balancing Robot with 80 mm wheels and bumper cage

Drawing date:
27 June 2018
Units: mm Material: mm
[in]


1. To get the specified scale, select $100 \%$ in print settings.
2. Angles shown assume use of 80 mm wheels.

## Name:

Balboa 32U4 Balancing Robot with 80mm wheels and bumper cage

## Drawing date:

27 June 2018
Units: m
[in]
Material
Mixed

