

RoHS

0 to V<sub>CC</sub>V

500kHz(Max.)

-5.0 to 5.0A 0.35Ω(Typ.)

-30 to +85°C

# **H-Bridge Drivers for Brush Motors** 1ch.H-Bridge Driver **High-Speed Drive type**

# **BD65496MUV**

#### General Description

The BD65496MUV motor driver provides 1 Full-On Driver H-Bridge channel. This driver features wide range operating from 1.8V and low power consumption by fast switching speed in a compact surface mount package.

#### Features

- Low ON-Resistance Power DMOS output: upper & lower total  $0.35\Omega$  (Typ.)
- Range of motor power supply voltage: 1.8V to 16.0V
- Charge pump-less type with p-channel DMOS for the upper side transistor
- H-Bridge output current (DC): 1.2A
- H-Bridge output current (Peak2): 5.0A
- The highest performance in switching speed: 150ns(Turn on time), 50ns(Turn off time)
- Variable switching speed 4-values
- Drive mode switch function (EN/IN & IN/IN)
- Control input pins fit the signal of 1.8V system
- With built-in Under Voltage Locked Out protection & Thermal Shut Down circuit
- Stand-by current: 0µA (Typ.)

#### Applications

- Mobile system
- Home appliance
- Amusement system, etc

#### Key Specifications

- Power supply voltage range: 2.5V to 5.5V
- Motor power supply voltage range: 1.8V to 16.0V
  - Circuit Current (Open Mode): 0.80mA(Typ.) 1µA (Max.)
- Stand-by Current:
- Control input voltage:
- Logic input frequency:
- Minimum logic input pulse width:
- 0.2µs(Min.) ■ Turn On Time (TR1=TR2=Lo): 150ns(Typ.)
- Turn Off Time (TR1=TR2=Lo): 50ns(Typ.)
- H-Bridge output current (DC): -1.2 to 1.2A
- H-Bridge output current (Peak2):
- Output ON-Resistance (Total):
- Operating temperature Range:
- Package

VQFN024V4040

W(Typ.) x D(Typ.) x H(Max.) 4.00mm x 4.00mm x 1.00mm



## Ordering Information



# Block Diagram / Application Example

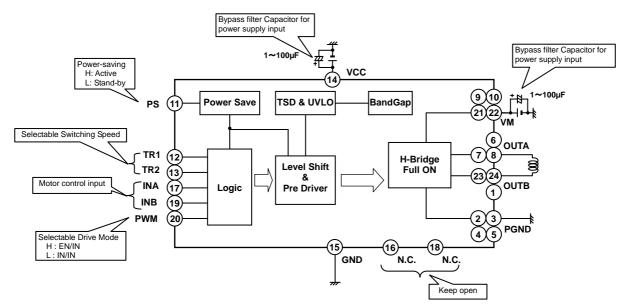


Figure 1. Block Diagram / Application Example

# Pin Configuration

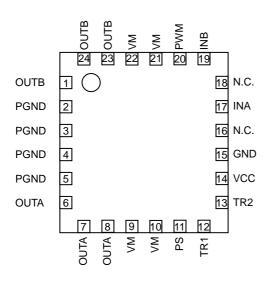


Figure 2. Pin Configuration (Top View)

Each of the same named terminals (VM, PGND, OUTA, OUTB) must be connected together on the PCB (Printed Circuit Board).

## Pin Description

No.	Name	Function
1	OUTB	H-bridge output terminal B
2	PGND	Motor ground terminal
3	PGND	Motor ground terminal
4	PGND	Motor ground terminal
5	PGND	Motor ground terminal
6	OUTA	H-bridge output terminal A
7	OUTA	H-bridge output terminal A
8	OUTA	H-bridge output terminal A
9	VM	Motor power supply terminal
10	VM	Motor power supply terminal
11	PS	Power-saving terminal
12	TR1	Turn On Time & Turn Off Time selection terminal 1
13	TR2	Turn On Time & Turn Off Time selection terminal 2
14	VCC	Power supply terminal
15	GND	Ground terminal
16	N.C.	-
17	INA	Control input terminal A
18	N.C.	-
19	INB	Control input terminal B
20	PWM	Drive mode selection pin
21	VM	Motor power supply terminal
22	VM	Motor power supply terminal
23	OUTB	H-bridge output terminal B
24	OUTB	H-bridge output terminal B

## ●Absolute Maximum Ratings (Ta=+25°C)

Parameter	Symbol	Limit	Unit	
Power supply voltage	V <sub>cc</sub>	-0.3 to +7.0	V	
Motor power supply voltage	V <sub>M</sub>	-0.3 to +20.0	V	
Control input voltage	V <sub>IN</sub>	-0.3 to V <sub>CC</sub> + 0.3	V	
		700 <sup>*1</sup>		
Power dissipation	Pd	2200 <sup>*2</sup>	mW	
		3560 <sup>*3</sup>		
H-bridge output current (DC)	Ι <sub>Ουτ</sub>	-1.2 to 1.2 <sup>*4</sup>		
H-bridge output current (Peak1 <sup>*5</sup> )	I <sub>OUTP1</sub>	-3.2 to 3.2 <sup>*4</sup>	А	
H-bridge output current (Peak2 <sup>*5</sup> )	I <sub>OUTP2</sub>	-5.0 to 5.0 <sup>*4</sup>		
Storage temperature range	T <sub>stg</sub>	-55 to +150	°C	
Junction temperature	T <sub>jmax</sub>	+150	°C	

\*1 Reduced by 5.6mW/°C over 25°C, when mounted on a glass epoxy 1-layer board (74.2mm × 74.2mm × 1.6mm)

In surface layer copper foil area: 10.29mm<sup>2</sup> \*2 Reduced by 17.6mW/°C over 25°C, when mounted on a glass epoxy 4-layer board (74.2mm × 74.2mm × 1.6mm) In surface & back layers copper foil area: 10.29mm<sup>2</sup>, 2&3 layers copper foil area: 5505mm<sup>2</sup>

\*3 Reduced by 28.4mW/°C over 25°C, when mounted on a glass epoxy 4-layer board (74.2mm × 74.2mm × 1.6mm) In all 4-layers copper foil area: 5505mm<sup>2</sup>

\*4 Must not exceed Pd, ASO, or Tjmax of 150°C.

\*5 Peak1=100ms (Duty≦20%). Peak2=10ms (Duty≦5%)

#### Recommended Operating Ratings

Parameter	Symbol	Limit	Unit
Power supply voltage	V <sub>cc</sub>	2.5 to 5.5	V
Motor power supply voltage	V <sub>M</sub>	1.8 to 16.0	V
Control input voltage	V <sub>IN</sub>	0 to V <sub>CC</sub>	V
Logic input frequency	F <sub>IN</sub>	0 to 500	kHz
Min. logic input pulse width	T <sub>IN</sub>	0.2 <sup>*6</sup>	μs
Operating temperature Range	T <sub>opr</sub>	-30 to +85	°C

\*6 TR1=TR2=Lo

# ●Electrical Characteristics (Unless otherwise specified Ta=+25°C, V<sub>cc</sub>=3.0V, V<sub>M</sub>=5.0V)

Deveneter	Limit		1.1	O and distingt			
Parameter	Symbol	Min.	Тур.	Max.	Unit	Condition	
All Circuits			r.				
Stand-by Current	I <sub>CCST</sub>	-	0	1	μA	V <sub>PS</sub> =0V	
Circuit Current 1	I <sub>CC1</sub>	0.50	0.80	1.25	mA	V <sub>PS</sub> =3V, Open Mode	
Circuit Current 2	I <sub>CC2</sub>	0.50	0.85	1.30	mA	V <sub>PS</sub> =3V, CW & CCW Mode	
Circuit Current 3	I <sub>CC3</sub>	0.50	0.85	1.30	mA	V <sub>PS</sub> =3V, Short Brake Mode	
PS Input (PS)							
High-level input voltage	V <sub>PSH</sub>	1.45	-	V <sub>CC</sub>	V		
Low-level input voltage	V <sub>PSL</sub>	0	-	0.5	V		
High-level input current	I <sub>PSH</sub>	15	30	60	μA	V <sub>PS</sub> =3V	
Low-level input current	I <sub>PSL</sub>	-1	0	1	μA	V <sub>PS</sub> =0V	
Control Input (IN=INA, INB, PV	VM, TR1, T	R2)					
High-level input voltage	V <sub>INH</sub>	1.45	-	V <sub>CC</sub>	V		
Low-level input voltage	V <sub>INL</sub>	0	-	0.5	V		
High-level input current	I <sub>INH</sub>	15	30	60	μA	V <sub>IN</sub> =3V	
Low-level input current	I <sub>INL</sub>	-1	0	1	μA	V <sub>IN</sub> =0V	
Under Voltage Locked Out (UV	/LO)						
UVLO Voltage	V <sub>UVLO</sub>	2.0	-	2.4	V		
Full ON type H-Bridge Driver							
Output ON-Resistance	R <sub>ON</sub>	-	0.35	0.50	Ω	I <sub>OUT</sub> =±500mA, Upper & Lower total	
Turn On Time 0	T <sub>ON0</sub>	-	150	300	ns	20Ω Loading, TR1=Lo, TR2=Lo	
Turn Off Time 0	T <sub>OFF0</sub>	-	50	200	ns	20Ω Loading, TR1=Lo, TR2=Lo	
Turn On Time 1	T <sub>ON1</sub>	-	250	500	ns	20Ω Loading, TR1=Hi, TR2=Lo	
Turn Off Time 1	T <sub>OFF1</sub>	-	70	200	ns	20Ω Loading, TR1=Hi, TR2=Lo	
Turn On Time 2	T <sub>ON2</sub>	-	350	800	ns	20Ω Loading, TR1=Lo, TR2=Hi	
Turn Off Time 2	T <sub>OFF2</sub>	-	90	250	ns	20Ω Loading, TR1=Lo, TR2=Hi	
Turn On Time 3	T <sub>ON3</sub>	-	500	1000	ns	20Ω Loading, TR1=Hi, TR2=Hi	
Turn Off Time 3	T <sub>OFF3</sub>	-	110	250	ns	20Ω Loading, TR1=Hi, TR2=Hi	

# Typical Performance Curves (reference data)

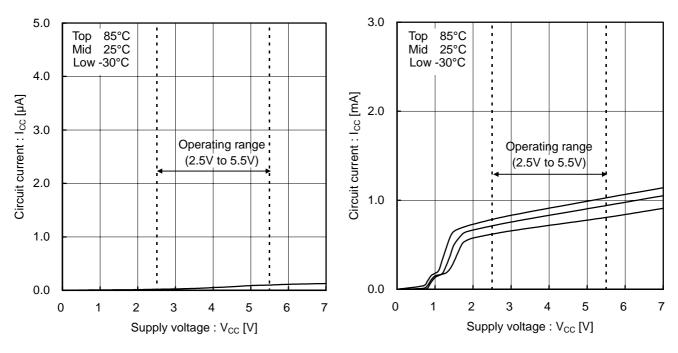
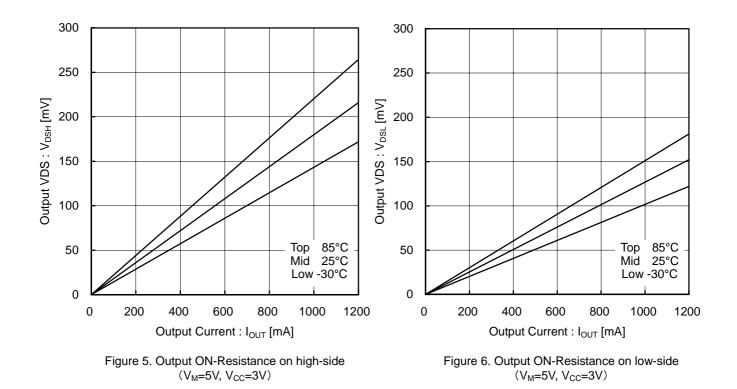


Figure 3. Circuit Current(Stand-by Mode)

Figure 4. Circuit Current(Open Mode)



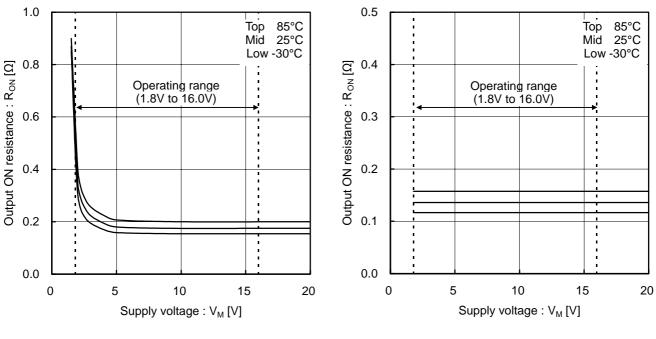


Figure 7. Output ON-Resistance on high-side  $(V_M \text{ Dependency}, V_{CC}=3V)$ 

Figure 8. Output ON-Resistance on low-side  $(V_M Dependency, V_{CC}=3V)$ 

## Description of Blocks

1) Power-saving function

When Low-level voltage is applied to PS pin, the IC will be turned off internally. During operating mode, PS pin should be High-level. (See the Electrical Characteristics; p.4/12, and Timing Chart; p.7/12)

2) Control Input: INA and INB

These pins are used to program and control the motor drive modes. (See the Electrical Characteristics; p.4/12, and Timing Chart; p.7/12)

- Control Input: PWM When the High-level voltage is applied to the PWM pin, the I/O logic can be set to EN/IN mode. However, when the Low-level, the I/O logic can be set to IN/IN mode. (See the Electrical Characteristics; p.4/12, and Timing Chart; p.7/12)
- 4) Control Input: TR1 and TR2

These pins are used to program and control the switching speed, turn on time and turn off time. (See the Electrical Characteristics; p.4/12, and Timing Chart; p.7/12)

# Timing Chart

Input Mode		INPUT			OUTPUT		
Input Mode	PS	PWM	INA	INB	OUTA	OUTB	Output Mode
		H L	L	Х	L	L	Short Brake
EN/IN	н		Н	L	Н	L	CW
			Н	Н	L	Н	CCW
			L	L	Z	Z	Open
			Н	L	Н	L	CW
IN/IN			L	Н	L	Н	CCW
			Н	Н	L	L	Short Brake
-	L	Х	Х	Х	Z	Z	Open

L; Low, H; High, X; Don't care, Z; Hi impedance

PS=High; Operation Mode, PS=Low; Stand-by Mode

CW; current flows from OUTA to OUTB, CCW; current flows from OUTB to OUTA

TR1	TR2	Turn ON Time [ns]	Turn Off Time [ns]
L	L	150	50
Н	L	250	70
L	Н	350	90
Н	Н	500	110

L: Low, H: High

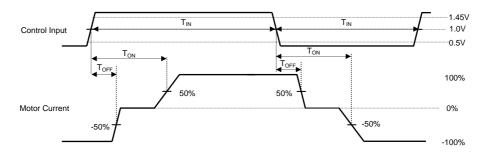


Figure 9. Input-Output AC definition

# Power Dissipation

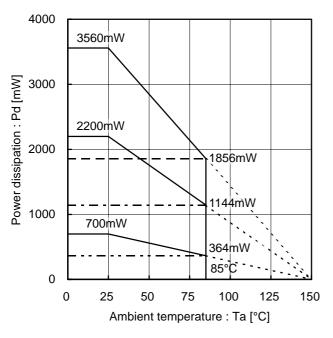


Figure 10. Power Dissipation Curve

# ●I/O equivalence circuit

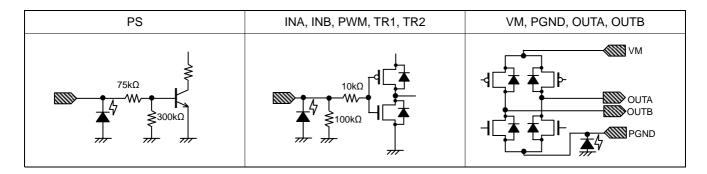


Figure 11. I/O equivalence circuit

## Operational Notes

1) Absolute maximum ratings

Use of the IC in excess of absolute maximum ratings such as the applied voltage or operating temperature range (Topr) may result in IC damage. Assumptions should not be made regarding the state of the IC (short mode or open mode) when such damage is suffered. The implementation of a physical safety measure such as a fuse should be considered when use of the IC in a special mode where the absolute maximum ratings may be exceeded is anticipated.

2) Power supply pins and lines

None of the VM line for the H-bridge is internally connected to the VCC power supply line, which is only for the control logic or analog circuit. Therefore, the VM and VCC lines can be driven at different voltages. Although these lines can be connected to a common power supply, do not open the power supply pin but connect it to the power supply externally.

Regenerated current may flow as a result of the motor's back electromotive force. Insert capacitors between the power supply and ground pins to serve as a route for regenerated current. Determine the capacitance in full consideration of all the characteristics of the electrolytic capacitor, because the electrolytic capacitor may loose some capacitance at low temperatures. If the connected power supply does not have sufficient current absorption capacity, regenerative current will cause the voltage on the power supply line to rise, which combined with the product and its peripheral circuitry may exceed the absolute maximum ratings. It is recommended to implement a physical safety measure such as the insertion of a voltage clamp diode between the power supply and ground pins. For this IC with 2 power supplies and a part consists of the CMOS block, it is possible that rush current may flow instantaneously due to the internal powering sequence and delays, and to the unstable internal logic, respectively. Therefore, give special consideration to power coupling capacitance, width of power and ground wirings, and routing of wiring.

3) Ground pins and lines

Ensure a minimum GND pin potential in all operating conditions. Make sure that no pins are at a voltage below the GND at any time, regardless of whether it is a transient signal or not.

When using both small signal GND and large current PGND patterns, it is recommended to isolate the two ground patterns, placing a single ground point at the application's reference point so that the pattern wiring resistance and voltage variations caused by large currents do not cause variations in the small signal ground voltage. Be careful not to change the GND wiring pattern of any external components, either.

The power supply and ground lines must be as short and thick as possible to reduce line impedance.

#### 4) Thermal design

Use a thermal design that allows for a sufficient margin in light of the power dissipation (Pd) in actual operating conditions.

5) Actions in strong magnetic field

Use caution when using the IC in the presence of a strong magnetic field as doing so may cause the IC to malfunction.

6) ASO

When using the IC, set the output transistor for the motor so that it does not exceed absolute maximum ratings or ASO.

7) Thermal shutdown circuit

This IC incorporates a TSD (thermal shutdown) circuit. If the temperature of the chip reaches the following temperature, the motor coil output will be opened. The TSD circuit is designed only to shut the IC off to prevent runaway thermal operation. It is not designed to protect the IC or guarantee its operation. Do not continue to use the IC after operating this circuit or use the IC in an environment where the operation of this circuit is assumed.

TSD ON temperature [°C] (Typ.)	Hysteresis temperature [°C] (Typ.)	
175	20	

8) N.C. PIN

Always keep N.C. pins open.

9) Application example

The application circuit is recommended for use. Make sure to confirm the adequacy of the characteristics. When using the circuit with changes to the external circuit constants, make sure to leave an adequate margin for external components including static and transitional characteristics as well as dispersion of the IC.

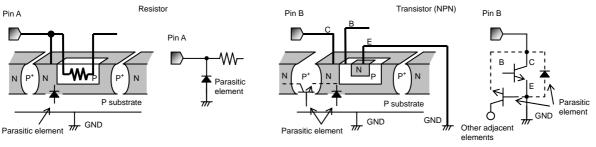


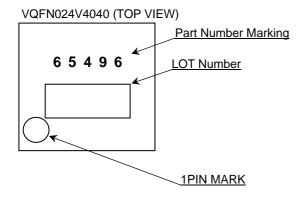
Figure 12. Example of Simple IC Architecture

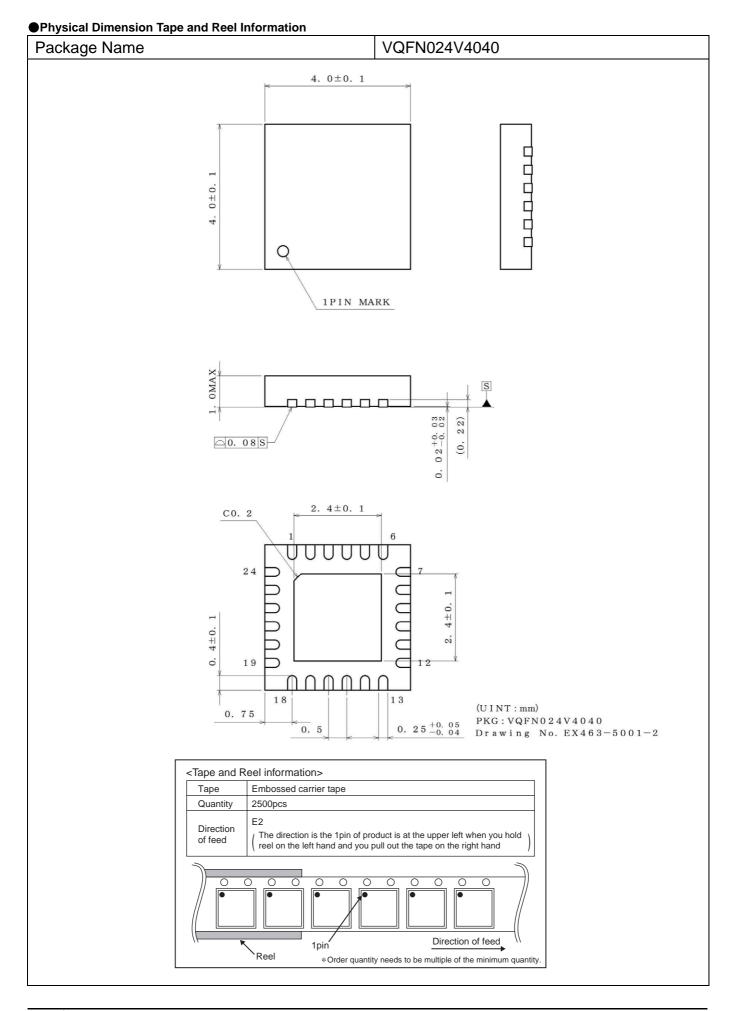
Status of this document

The Japanese version of this document is formal specification.

A customer may use this translation version only for a reference to help reading the formal version. If there are any differences in translation version of this document, formal version takes priority.

#### Marking Diagram





## Revision History

Date	Revision	Changes
11.May.2013	001	New release

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  - [g] Use of our Products without cleaning residue of flux (even if you use no-clean type fluxes, cleaning residue of flux is recommended); or Washing our Products by using water or water-soluble cleaning agents for cleaning residue after soldering
  - [h] Use of the Products in places subject to dew condensation
- 4. The Products are not subject to radiation-proof design.
- 5. Please verify and confirm characteristics of the final or mounted products in using the Products.
- 6. In particular, if a transient load (a large amount of load applied in a short period of time, such as pulse. is applied, confirmation of performance characteristics after on-board mounting is strongly recommended. Avoid applying power exceeding normal rated power; exceeding the power rating under steady-state loading condition may negatively affect product performance and reliability.
- 7. De-rate Power Dissipation (Pd) depending on Ambient temperature (Ta). When used in sealed area, confirm the actual ambient temperature.
- 8. Confirm that operation temperature is within the specified range described in the product specification.
- 9. ROHM shall not be in any way responsible or liable for failure induced under deviant condition from what is defined in this document.

#### Precaution for Mounting / Circuit board design

- 1. When a highly active halogenous (chlorine, bromine, etc.) flux is used, the residue of flux may negatively affect product performance and reliability.
- 2. In principle, the reflow soldering method must be used; if flow soldering method is preferred, please consult with the ROHM representative in advance.

For details, please refer to ROHM Mounting specification

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  - [d] the Products are exposed to high Electrostatic
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- 3. Store / transport cartons in the correct direction, which is indicated on a carton with a symbol. Otherwise bent leads may occur due to excessive stress applied when dropping of a carton.
- 4. Use Products within the specified time after opening a humidity barrier bag. Baking is required before using Products of which storage time is exceeding the recommended storage time period.

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