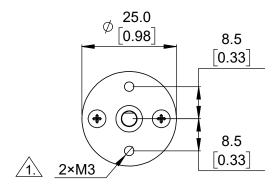
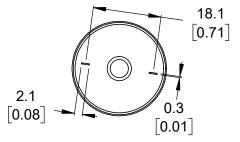


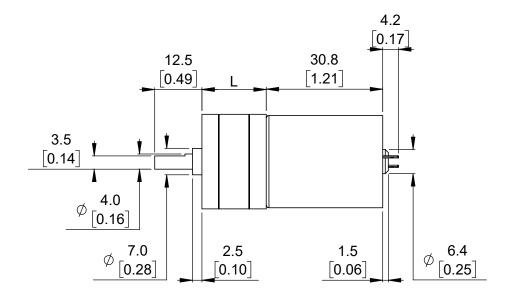
Gear ratio	L
4.4:1	17 mm [0.68 in]
9.7:1	
20.4:1	19 mm [0.75 in]
34:1	21 mm [0.83 in]
47:1	
75:1	23 mm [0.91 in]
99:1	
172:1	25 mm [0.98 in]
227:1	
378:1	27 mm [1.06 in]
499:1	







Depth of mounting holes is 6.0 mm [0.24 in]. To get the specified scale, select 100% in print settings.



https://www.pololu.com/category/115/25d-mm-gearmotors

mixed

Name: Metal Gearmotor 25D mm (without encoder)

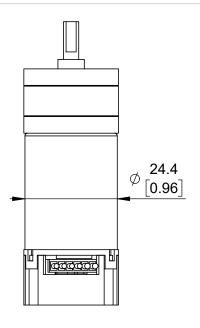
[in]

Drawing date: Dev code: 8 February 2019 Units: mm Material:

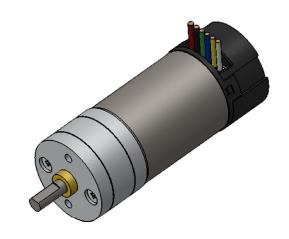
Scale: 1:1

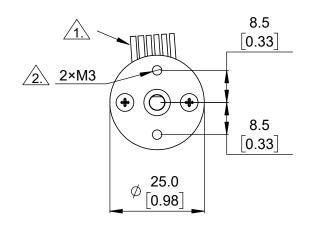


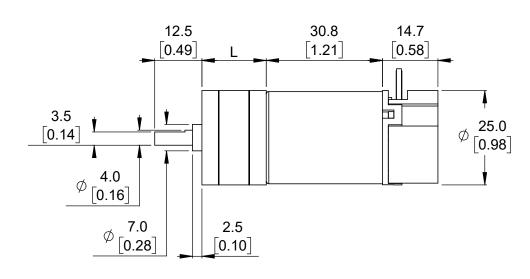
Item number:



Gear ratio	L
4.4:1	17 mm [0.68 in]
9.7:1	
20.4:1	19 mm [0.75 in]
34:1	21 mm [0.83 in]
47:1	
75:1	23 mm [0.91 in]
99:1	
172:1	25 mm [0.98 in]
227:1	
378:1	27 mm [1.06 in]
499:1	









Leads are approximately 200 mm [8 in] long and are terminated by a 1×6 female header with a 2.54 mm [0.1 in] pitch. Depth of mounting holes is 6.0 mm [0.24 in]. To get the specified scale, select 100% in print settings.

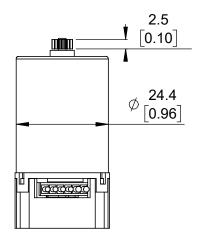
Scale: 1:1

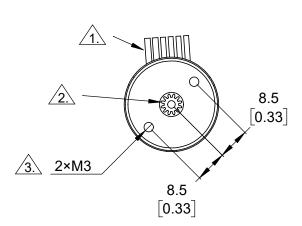
https://www.pololu.com/category/115/25d-mm-gearmotors Name: Item number: 4801-4811, 4821-4831, 4841-4851, 4861-4871 4881-4891 Metal Gearmotor 25D mm with 48 CPR Encoder

Drawing date: Dev code: 8 February 2019

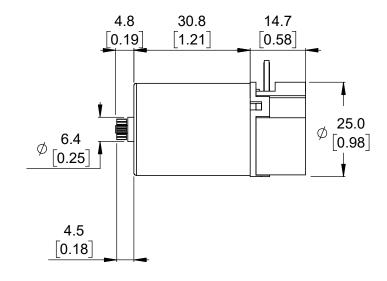
Units: mm Material: [in] mixed













Leads are approximately 200 mm [8 in] long and are terminated by a 1×6 female header with a 2.54 mm [0.1 in] pitch. The non-removable pinion gear has a metric module 0.4, 12 teeth, and a 20° pressure angle. Depth of mounting holes is 2.0 mm [0.08 in]. To get the specified scale, select 100% in print settings.

https://www.pololu.com/category/115/25d-mm-gearmotors Item number: 4800, 4820, 4840, 4860, 4880 Motor with 48 CPR Encoder for

25D mm Metal Gearmotors (no gearbox)

Drawing date: Dev code: 8 February 2019

Units: mm Material: [in] mixed

